



## Numerik für Differentialgleichungen – SoSe 2023

Sheet 4

Ausgabe: 14.06.2023, 12:00 Uhr

Abgabe: 21.06.2023, 12:00 Uhr

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**Homepage to the lecture:**

<https://aam.uni-freiburg.de/agasa/lehre/ss23/ndgln>

**Exercise 1** (4 points). Which quadrature formulas are the basis of the *classical Runge-Kutta method*, the *3/8-rule* and the *Radau-3 method* and which degrees of exactness do they have?

**Exercise 2** (4 points). Determine the Butcher-Tableau for the Runge-Kutta method defined by the following increment function:

$$\begin{aligned}\phi(t, y, \tau) &= \frac{1}{6}(\eta_1 + 4\eta_2 + \eta_3), \\ \eta_1 &= f(t, y), \\ \eta_2 &= f(t + \tau/2, y + \tau\eta_1/2), \\ \eta_3 &= f(t + \tau, y + \tau(-\eta_1 + 2\eta_2)).\end{aligned}$$

Prove that this method has consistency order  $p = 3$ .

**Exercise 3** (4 points). Derive sufficient conditions for the third order consistency of a *Runge-Kutta method* for the case of autonomous differential equations.

*Hint: Use the derivation of a sufficient condition for the second order consistency from Remark 22.5 in the book Numerics 3x9.*

**Exercise 4** (1 + 3 points). Let  $A \in \mathbb{R}^{m \times m}$  such that  $\|A\| < 1$  with respect to an operator norm  $\|\cdot\|$ .

- (i) Prove that  $(E_m - A)$  is invertible with inverse  $(E_m - A)^{-1} = \sum_{n=0}^{\infty} A^n$ .
- (ii) Formulate *Newton's method* for solving the fixed point equation  $\eta = \Phi(\eta)$  for determining a coefficient vector  $\eta \in \mathbb{R}$  in a *Runge-Kutta method* and discuss its well-posedness.