
NASDE 15.10.2024



Famous model in biology:
Lotka-Volterra (predator-prey) ①

$$\frac{dx}{dt} = x(\alpha - \beta y) \quad (*) \quad \alpha, \beta, \gamma > 0$$

$$\frac{dy}{dt} = y(\gamma x - \gamma)$$

x - population density of prey (# of rabbits per km^2)
 y - - - - of predator (fox)

$\frac{dx}{dt}, \frac{dy}{dt}$ - growth rate

* prey reproduce exponentially with α ,
subject to predation $\beta x y$

* $\gamma x y$ - growth of predator subject to
 $\gamma \cdot y \leftarrow$ loss due to natural causes

②
 \rightarrow can also be used in economics

Assum: no environmental changes

However: temperature, flood, earthquake,

\rightarrow Hard to model deterministically
 \rightarrow Some uncertainty, randomness exists \Rightarrow

Stochastic version of (*):

$$dX = x(\alpha - \beta y)dt + C_1 \cdot x \cdot dW_t^{(1)}$$

$$dY = y(\gamma x - \gamma)dt + C_2 \cdot y \cdot dW_t^{(2)}$$

$W = (W^{(1)} \quad W^{(2)})$ - 2 dim - l Brownian motion

SDEs in the form

$$dX_t = \underbrace{\mu(X_t)}_{\text{drift parameter}} dt + \underbrace{\sigma(X_t)}_{\text{diffusion parameter}} dW_t$$

(3)

(iii) $B_1, B_2, \dots \in \mathcal{A} \Rightarrow$ (4)
 $\bigcup_{i=1}^{\infty} B_i \in \mathcal{A}$ (closed under countable union)

Eg: $\mathcal{A} = \{\emptyset, \Omega\}$, $\mathcal{A} = \mathcal{P}(\Omega)$

First preliminaries from measure and probability theory:

We will work on a probability space (Ω, \mathcal{A}, P)

Ω is the underlying set
 \mathcal{A} is a σ -algebra on Ω
 P is the probability measure

Def-n \mathcal{A} is a σ -algebra on Ω if

(i) $\mathcal{A} \subset \mathcal{P}(\Omega)$ (power set of Ω , set of all subsets), $\emptyset \in \mathcal{A}$

(ii) $B \in \mathcal{A} \Rightarrow B^c = \Omega \setminus B \in \mathcal{A}$ (closed under complementation)

Q: what if $\mathcal{A} \subset \mathcal{P}(\Omega)$ is not a sigma-algebra?

Def: Sigma-algebra generated by \mathcal{A}

$$\sigma_{\Omega}(\mathcal{A}) = \bigcap B$$

B is a σ -algebra
 $B \supseteq \mathcal{A}$

If \mathcal{A} is a σ -algebra

$$\sigma_{\Omega}(\mathcal{A}) = \mathcal{A}$$

→ the smallest σ -algebra containing \mathcal{A} .

Def-n (Ω, \mathcal{A}) -measurable space,
 $\mu: \mathcal{A} \rightarrow [0, \infty]$. Then μ is a measure

(i) $\mu(\emptyset) = 0$

(ii) Sigma additivity:

$$\forall B_1, B_2, \dots \in \mathcal{A} \quad B_i \cap B_j = \emptyset, i \neq j$$

$$\mu\left(\bigcup_{i=1}^{\infty} B_i\right) = \sum_{i=1}^{\infty} \mu(B_i)$$

$(\Omega, \mathcal{A}, \mu)$ - measure space

If, $\mu(\Omega) = 1$ ⇒ probability space

(5)

Def Given 2 measurable spaces
 $(\Omega, \mathcal{A}), (\tilde{\Omega}, \tilde{\mathcal{A}})$, the function

$X: \Omega \rightarrow \tilde{\Omega}$ is $\mathcal{A}/\tilde{\mathcal{A}}$ measurable
(or just measurable) if

$$\forall S \in \tilde{\mathcal{A}}:$$

$$X^{-1}(S) = \{\omega \in \Omega : X(\omega) \in S\} \in \mathcal{A}$$

→ Given measurable f-n X one
can define σ -algebra generated by
 X

$$\sigma_{\Omega}(X) = \{X^{-1}(S), S \in \tilde{\mathcal{A}}\} \\ \subseteq \mathcal{A}$$

→ If in addition (Ω, \mathcal{A}, P) prob. space
 X is called a random variable.

(6)

Given a measure space $(\Omega, \mathcal{A}, \mu)$ and measurable $f: \Omega \rightarrow \mathbb{R}$

$$f: \Omega \rightarrow \mathbb{R}$$

one can define the integral

$$\int_{\Omega} f d\mu$$

[if $\mu = \mathbb{P}$, $\mathbb{E}[X]$] in 3 steps:

(1) $f: \Omega \rightarrow [0, \infty)$ meas, simple, i.e.

$$\# f(\Omega) < \infty$$

$$\int_{\Omega} f d\mu := \sum_{y \in f(\Omega)} y \cdot \mu(f^{-1}(y))$$

E.g. $f(\Omega) = \{1, 2\}$

$$\int f d\mu = 1 \cdot \mu(f^{-1}(1)) + 2 \cdot \mu(f^{-1}(2))$$

(2) All simple f , s.t. $f \leq X$ take sup of their integrals

$$\int X d\mu = \sup_{\substack{f \leq X \\ f \text{ simple}}} \left(\int f d\mu \right), X \geq 0$$

(3) $X = \max\{X, 0\} - \max\{-X, 0\}$

$$X \geq 0: \text{RHS} = X - 0 = X$$

$$X < 0: \text{RHS} = 0 - (-X) = X$$

Define

$$\int_{\Omega} X d\mu = \underbrace{\int_{\Omega} \max\{X, 0\} d\mu}_{\text{has to be } < \infty} - \underbrace{\int_{\Omega} \max\{-X, 0\} d\mu}_{\text{has to be } < \infty}$$

has to be $< \infty$ has to be $< \infty$

Variance

$$\text{Var}_p(X) = \mathbb{E}_p[(X - \mathbb{E}_p[X])^2]$$

$$\text{Cov}_p(X, Y) = \mathbb{E}_p[(X - \mathbb{E}_p[X]) \cdot (Y - \mathbb{E}_p[Y])]$$

$$\text{Cov}(X, X) = \text{Var}(X)$$

If $\text{Cov}(X, Y) = 0 \Rightarrow$ The random variables X and Y are uncorrelated

Every RV (random variable) has so-called distribution fn.

$$F(y) = P(X \leq y)$$

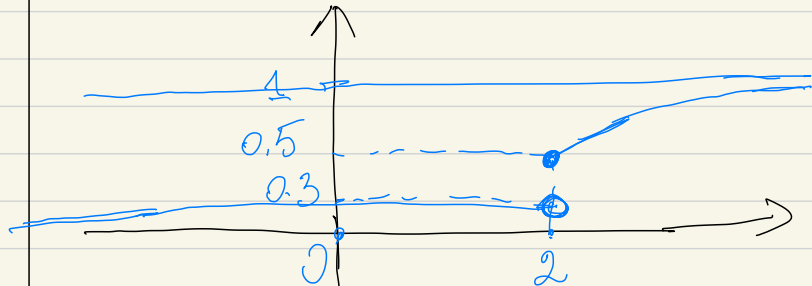
(9)

Def-n: $F: \mathbb{R} \rightarrow [0, 1]$ is called a distribution fn (10)

(i) F is non-decreasing
($x \leq y \Rightarrow F(x) \leq F(y)$)

(ii) $\lim_{x \rightarrow +\infty} F(x) = 1$, $\lim_{x \rightarrow -\infty} F(x) = 0$

(iii) F is càdlàg (i.e. right continuous, left limits)



$$F(2) = 0.5 = \lim_{x \nearrow 2} F(x)$$

$$\lim_{x \nearrow 2} F(x) = 0.3 \neq F(2)$$

Examples: Discrete or continuous uniform distribution (1)

Discrete: Finite number of possible events with the same probability.

Continuous: $A \in \mathcal{B}(\mathbb{R})$ (Borel set) with

$$0 < \lambda(A) < \infty$$

$\hat{=}$ Lebesgue-Borel measure on \mathbb{R}

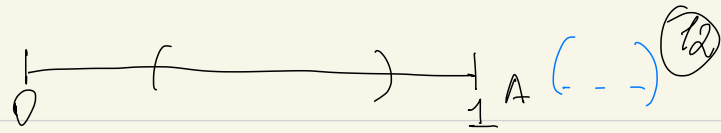
$$\mu_A: \mathcal{B}(\mathbb{R}) \rightarrow [0, \infty]$$

$$\mu_A(B) = \frac{\lambda(B \cap A)}{\lambda(A)}$$

Continuous uniform distribution on A

E.g. $A = (0, 1)$, $\lambda(A) = 1$

$$B = \left(\frac{1}{2}, \frac{3}{4}\right)$$



$$\mu_A(B) = \lambda(B) = \frac{1}{4}$$

$$\mu_A(A) = 1$$

(2) Normal distribution:

$\mathcal{N}_{0, \mathbb{I}_{\mathbb{R}^d}}$: $\mathcal{B}(\mathbb{R}^d) \rightarrow [0, \infty]$
 $\mathbb{I}_{\mathbb{R}^d}$ - Identity matrix on \mathbb{R}^d

$$\mathbb{I}_{\mathbb{R}^d} = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

$$\mathcal{N}_{0, \mathbb{I}_{\mathbb{R}^d}}(B) = \frac{1}{(2\pi)^{d/2}} \int_B e^{-\frac{1}{2} \|x\|^2} dx$$

If $v \in \mathbb{R}^d$, $Q \in \mathbb{R}^{d \times d}$ nonnegative symmetric (13)

$$\mathcal{N}_{v, Q}(B) = \mathcal{N}_{v, \mathbb{R}^d}(x \in \mathbb{R}^d : \sqrt{Q}x + v \in B)$$

X is $\mathcal{N}_{v, Q}$ distributed

$$\mathbb{E}_p[X] = v$$

$$X = (X^{(1)}, \dots, X^{(d)})$$

$$\mathbb{E}[X] = \begin{pmatrix} \mathbb{E}[X^{(1)}] \\ \mathbb{E}[X^{(2)}] \\ \vdots \\ \mathbb{E}[X^{(d)}] \end{pmatrix} \in \mathbb{R}^d$$

$$\text{Var}(X) \in \mathbb{R}^{d \times d}, (\text{Var}(X))_{i,j} =$$

$$= \text{Cov}(X^{(i)}, X^{(j)})$$

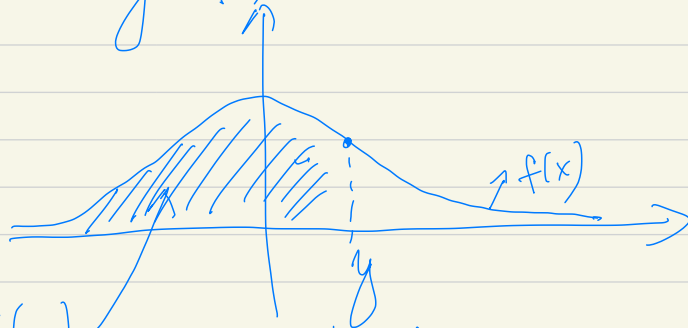
$$\text{Var}(X) = Q \in \mathbb{R}^{d \times d}$$

Transformation formula

$$A \in \mathbb{R}^{d \times d}, b \in \mathbb{R}^d, X \sim \mathcal{N}_{v, Q}$$

$$AX + b \sim \mathcal{N}_{Av+b, AQA^T}$$

Density $f(x)$



$F(y)$ - area under the curve f up to y .

Next-time - generation of (pseudo) random numbers

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