Practical Sheet 2

Note that we do not distinguish between pseudo random numbers and actual random numbers.

1. a) Write a MATLAB function RecRule(a,b,d,n,f) with input $a \in \mathbb{R}$, $b \in (a, \infty)$, $d, n \in \mathbb{N}$, $f: [a, b]^d \to \mathbb{R} \in \mathcal{L}^1(B_{[a, b]^d}; |\cdot|_{\mathbb{R}})$ and output $R^n_{[a, b]^d}[f]$.

Hint: Implement the evaluation of f in the rectangle rule *recursively*. To this end, write a subroutine RecRuleRecursion(f,...,d). Specify the remaining input parameters of the recursion, and use the following (rough) structure for your code:

1: procedure RECRULERECURSION(f,...,d) if d > 1 then 2: for $i_d \in \{0, ..., n-1\}$ do 3: Fix the *d*-th coordinate $x_{d,i_d} := a + \frac{i_d}{n}(b-a)$. 4: Evaluate the (d-1)-dimensional integral with respect 5: to the domain $[a,b]^{(d-1)} \times \{x_{d,i_d}\}$ by calling 6: 7: RecRuleRecursion(f, ..., d-1) and add the result 8: to the overall approximation. end for 9: else 10: Use the one-dimensional rectangle rule and add the result 11: 12:to the overall approximation. end if 13:14: end procedure

b) Let a = 0, b = 1 and let $f = [0, 1]^d \ni (x_1, \ldots, x_d) \mapsto x_1 \in \mathbb{R}$. Test your implementation by computing

$$\left| R^n_{[a,b]^d}[f] - \int_{[a,b]^d} f(x) \, dx \right|_{\mathbb{R}} \tag{1}$$

for $n \in \{2^4, 2^5, \ldots, 2^{10}\}$, $d \in \{1, 2, 3\}$, and measure the execution time for each d and n. For each d, plot the error in Eq. (1) against the execution time. Plot all three error curves in one diagram with logarithmic scale and times on the x-axis.

Hint: Use the built-in function loglog to generate a logarithmic plot.

2. Let $d \in \mathbb{N}$, $a \in \mathbb{R}$, $b \in (a, \infty)$, $f \in \mathcal{L}^1(B_{[a,b]^d}; |\cdot|_{\mathbb{R}})$, let (Ω, \mathcal{F}, P) be a probability space, and let $X_j: \Omega \to \mathbb{R}^d$, $j \in \mathbb{N}$, be a sequence of independent $\mathcal{U}_{[a,b]^d}$ -distributed random variables on (Ω, \mathcal{F}, P) . For all $N \in \mathbb{N}$ define the functions

$$I_N := \frac{(b-a)^d}{N} \left[\sum_{j=1}^N f(X_j) \right].$$
 (2)

The function I_N as in Eq. (2) is the Monte Carlo estimator of the integral

$$\int_{[a,b]^d} f(x) \, dx = (b-a)^d \mathbb{E}_P[f(X_1)].$$
(3)

- a) Write a MATLAB function intMC(a,b,d,N,f) with input $a \in \mathbb{R}, b \in (a,\infty)$, $d \in \mathbb{N}, f \in \mathcal{L}^1(B_{[a,b]^d}; |\cdot|_{\mathbb{R}}), N \in \mathbb{N}$ that outputs a realization of I_N .
- b) Test your MATLAB function intMC(a,b,d,f,N) by repeating the experiment from Problem 1, b) above: Let a = 0, b = 1 and let $f = [0,1]^d \ni (x_1,\ldots,x_d) \mapsto x_1 \in \mathbb{R}$. Test your implementation by computing

$$\left| I_N - \int_{[a,b]^d} f(x) \, dx \right|_{\mathbb{R}} \tag{4}$$

for $N \in \{2^{14}, 2^{15}, \ldots, 2^{20}\}$, $d \in \{1, 2, 3\}$, and measure the execution time for each d and n. Plot again the error for any dimension d against the execution time and compare the results to the rectangular rule from Problem 1.

3. Approximative realizations of a one-dimensional standard Brownian motion: Let A be the set given by

$$A = \bigcup_{n=1}^{\infty} \left\{ \mathbf{t} = (t_1, \dots, t_n) \in [0, \infty)^n \colon \#_{\mathbb{R}}(\{t_1, \dots, t_n\}) = n \right\},$$
(5)

let length: $A \to \mathbb{N}$ be the function which satisfies for all $n \in \mathbb{N}$, $\mathbf{t} = (t_1, \ldots, t_n) \in [0, \infty)^n \cap A$ that

$$length(\mathbf{t}) = n, \tag{6}$$

and let $Q: A \to (\bigcup_{n=1}^{\infty} \mathbb{R}^{n \times n})$ be the function which satisfies for all $n \in \mathbb{N}$, $\mathbf{t} = (t_1, \ldots, t_n) \in [0, \infty)^n \cap A$ that

$$Q(\mathbf{t}) = (\min\{t_i, t_j\})_{(i,j) \in \{1,\dots,n\}^2}.$$
(7)

Write a MATLAB function StandardBrownianMotion(t) with input $\mathbf{t} \in A$ and output a realization of an $\mathcal{N}_{0,Q(\mathbf{t})}$ -distributed random variable. The MATLAB function StandardBrownianMotion(t) may use at most length(t) realizations of an $\mathcal{N}_{0,I_{\mathbf{R}}}$ -distributed random variable. Call the MATLAB commands

```
1 rng('default');
2 N=10^3;
3 preimage = (0:1/N:1);
4 X=StandardBrownianMotion(preimage);
5 plot(preimage,X);
```

```
6 hold on
7 X=StandardBrownianMotion(preimage);
8 plot(preimage,X,'r');
9 X=StandardBrownianMotion(preimage);
10 plot(preimage,X,'g');
```

to test your implementation.

Due: Friday, 15.11.2024. Webpage: https://aam.uni-freiburg.de/agsa/lehre/ws24/numsde/index.html